2-Way High Performance Prop. Throttle Valve **Series TDC**

The 2-way high performance proportional throttle valves series TDC are used in applications where high flow has to be precisely controlled at high dynamics. Typical applications are die casting, injection moulding and hydraulic presses.

Function

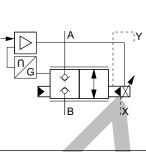
TDC040

The 2-way high performance proportional throttle valves TDC have a 2-stage design consisting of a proportional pilot valve and a main stage with poppet and LVDT.

With the pilot valve the TDC achieves fast response times: from 20 ms (NG25) up to 31 ms (NG50) with an accuracy of <0.7 % of the nominal flow. The pilot valve actively controls the poppet - independent of the pressure conditions in the main ports.

It is basically required that the pilot pressure is at the level of the system pressure. At low system pressure the pilot pressure should be min. 140 bar, when high valve dynamics are desired.

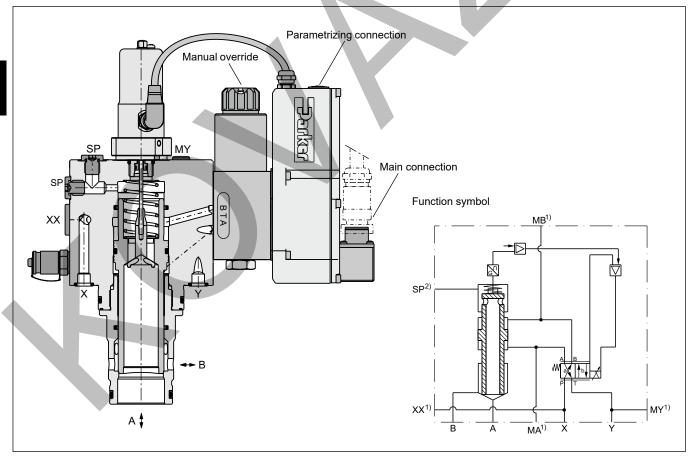




TDC040

Features

- Active pilot operated 2-way high performance proportional throttle valve
- Cavity and mounting pattern according to ISO 7368
- · Fast step response
- Flow direction B to A and A to B
- Completely mounted and adapted unit with integrated electronics
- In order to ensure the closed position, pilot pressure is required.
- 4 sizes NG25 up to NG50



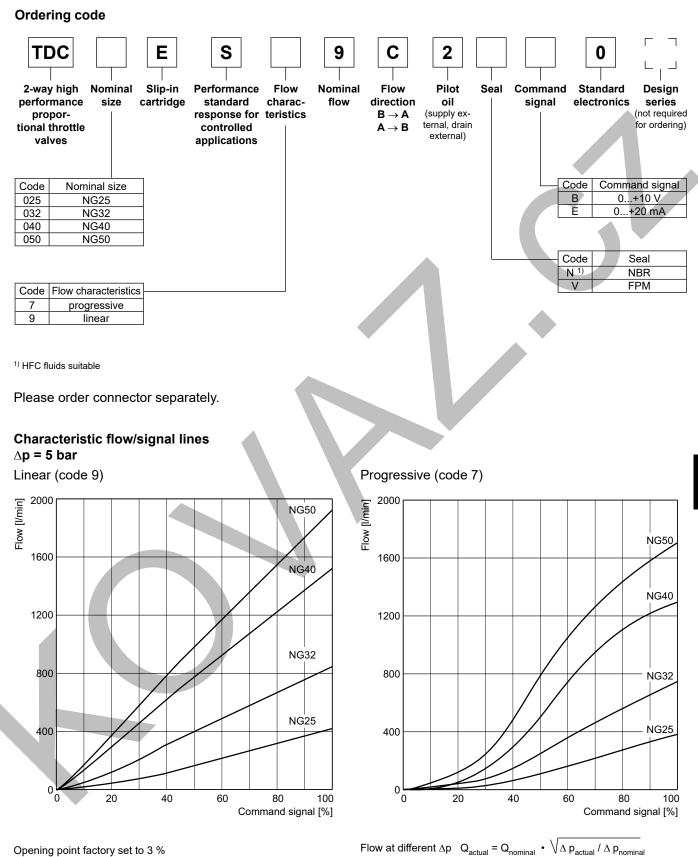
¹⁾ NG25 and NG32 without accu port XX and without ports MA, MB and MY.

²⁾ NG25 without suction port SP.

TDC UK 18.10.22



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Opening point factory set to 3 %

Characteristic curve measured with HLP46 at 50 °C.



2-Way High Performance Prop. Throttle Valve **Series TDC**

			Description of the set			the state of the		
Design					and integrated electron	iics, slip-in cartridge		
0			according to ISO 7368					
Nominal size		DIN		NG32	NG40	NG50		
Mounting position			unrestricted					
Ambient temperatu	re	[°C]		,		- <u>1</u>		
Weight		[kg]] 11	13	15	26		
Vibration resistance	÷	[9]		noise 202000	-6 Hz acc. IEC 68-2-36			
Hydraulic				00-2-21				
Max. operating pre	ssure	[bar	Ports A B X and	SP up to 350 XX	observe accumulator	r pressure rating:		
max. operating pro	50410	[buil	port Y: max. 210			procedure realing,		
Fluid			Hydraulic oil accor	ding to DIN 5152	24			
Fluid temperature		[°C] -20+60 (NBR: -2					
	ommended	[cSt] / [mm²/s]						
	mitted	[cSt] / [mm²/s]						
Filtration			ISO 4406; 18/16/1	3				
Nominal flow at Δp	= 5 har (linear)	[l/min		850	1500	1900		
Recommended ma		[l/min]		2000	3000	4500		
	= 5 bar (progressive)	[l/min]		750	1300	1700		
	x. flow (progressive)	[l/min]		1750	2600	4000		
Flow direction	. now (progressive)	[i/mn	B to A / A to B	1750	2000	4000		
Pilot pressure		[hor		a evetom procesur				
	and the	[bar]		s system pressur	e			
Pilot oil sup dra	oply		external via X					
		Free L/mail.or	external via Y					
Leakage in pilot va		[ml/min]] <400		NCOC			
Pilot valve size	10 h	FI (mailing)	00	00	NG06	40		
Max. pilot flow at 1	10 bar pilot pr.	[l/min]] 23	30	40	40		
Static/dynamic								
	s see installation recomm	,						
	ilot press. >140 bar	[ms		22	27	31		
Hysteresis] < 0.1					
Sensitivity		[%]] < 0.5					
Electrical								
Duty ratio		[%] 100						
Protection class				-N 60529 (with c	prrectly mounted plug	-in connector)		
	nla							
Supply voltage / rip			8 30, electric shut	-off at < 17, ripple	e < 5 % eff., surge fre	e		
Current consumption		[A] 2.0		-off at < 17, ripple	e < 5 % eff., surge fre	e		
Current consumption Pre-fusing		[A] 2.0	8 30, electric shut medium lag	-off at < 17, ripple	e < 5 % eff., surge free	9		
Current consumption Pre-fusing Input signal	on max.	[A] 2.0 [A] 2.5 A	medium lag		e < 5 % eff., surge free	e		
Current consumption Pre-fusing Input signal Code B Voltag	on max. ge	[A] 2.0 [A] 2.5 A			e < 5 % eff., surge free	e		
Current consumption Pre-fusing Input signal Code B Voltag	on max.	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100	medium lag I0, ripple < 0,01 % e	ff., surge free	e < 5 % eff., surge free	e		
Current consumption Pre-fusing Input signal Code B Voltag	on max. ge dance	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef	ff., surge free	e < 5 % eff., surge free	e		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped	on max. ge dance int dance	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef	ff., surge free f., surge free		e		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre	on max. ge dance int dance	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 for	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef) r terminal D and E a	ff., surge free f., surge free gainst PE (termir	al G)	e		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped	on max. ge dance int dance	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 for 11 for	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef	ff., surge free f., surge free gainst PE (termir	al G)	e		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped	on max. ge dance ont dance ax.	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 for 11 for [%] 050	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef) r terminal D and E ag)	ff., surge free f., surge free gainst PE (termir	al G)	e		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped Differential input m	on max. ge dance ont dance ax.	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 foi 11 foi [%] 050 [%] 501	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef) r terminal D and E ag r terminal D and E ag) 100	ff., surge free f., surge free gainst PE (termir	al G)	e		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped Differential input m	on max. ge dance ont dance ax. Min.	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 foi 11 foi [%] 050 [%] 501	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef) r terminal D and E ag r terminal D and E ag) 100	ff., surge free f., surge free gainst PE (termir	al G)	e 		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped Differential input m	on max. ge dance ont dance ax. Min. Max.	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 for 11 for [%] 050 [%] 501 [\$] 032	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef) r terminal D and E ag) terminal D and E ag) 2.5	ff., surge free f., surge free gainst PE (termir	al G)	e		
Current consumption Pre-fusing Input signal Code B Voltag Imper Code E Curre Imper Differential input m Adjustment ranges Enable signal	on max. ge dance ont dance ax. Min. Max.	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 for 11 for [%] 050 [%] 501 [%] 032 [V] 530	medium lag 10, ripple < 0,01 % e 20, ripple <0,01 % ef r terminal D and E ag r terminal D and E ag 0 100 2.5	ff., surge free f., surge free gainst PE (termin gainst 0V (termin	al G) al B)	e 		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped Differential input m Adjustment ranges Enable signal Diagnostic signal	on max. ge dance ont dance ax. Min. Max.	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 for 11 for [%] 050 [%] 501 [%] 032 [V] 530 [V] 0+1	medium lag 10, ripple < 0,01 % ef 20, ripple <0,01 % ef r terminal D and E ag r terminal D and E ag 100 2.5 10 / +12.5 error detect	ff., surge free f., surge free gainst PE (termin gainst 0V (termin ction, rated max.	al G) al B)	e		
Current consumption Pre-fusing Input signal Code B Voltag Imper Code E Curre Imper Differential input m Adjustment ranges Enable signal Diagnostic signal EMC	on max. ge dance ant dance ax. Min. Max. Ramp	[A] 2.0 [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 foi 11 foi [%] 050 [%] 501 [%] 032 [V] 530 [V] 0+1 EN 6	medium lag 10, ripple < 0,01 % ef 20, ripple <0,01 % ef r terminal D and E ag (00 2.5 1000-6-2, EN 61000	ff., surge free f., surge free gainst PE (termin gainst 0V (termin ction, rated max. -6-4	al G) al B)	e		
Current consumption Pre-fusing Input signal Code B Voltag Imped Code E Curre Imped Differential input m Adjustment ranges Enable signal Diagnostic signal	on max. ge dance ant dance ax. Min. Max. Ramp	[A] 2.0 [A] 2.5 A [A] 2.5 A [V] 0+1 [kOhm] 100 [mA] 0+2 [Ohm] < 250 [V] 30 for 11 for [%] 050 [%] 501 [%] 501 [%] 504 [%] 504 [V] 530 [V] 0+1 EN 6 6 + P	medium lag 10, ripple < 0,01 % ef 20, ripple <0,01 % ef r terminal D and E ag r terminal D and E ag 100 2.5 10 / +12.5 error detect	ff., surge free f., surge free gainst PE (termin gainst 0V (termin ction, rated max. -6-4 04	al G) al B)	e		

Installation recommendation (NG40 + NG50)

An insufficient pilot oil supply (e.g. due to long distances and/or small diameters) can negatively influence the dynamics of the TDC valve.

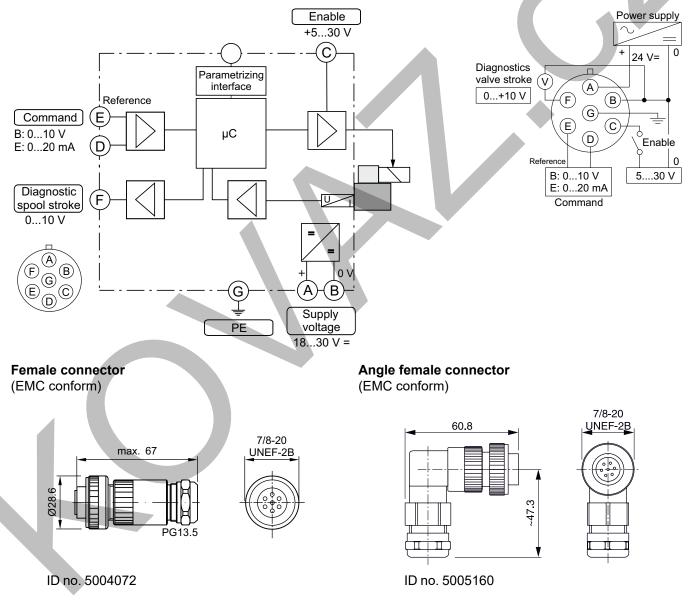
To avoid this, an accumulator can be connected to port XX at the valve body of the TDC. A short-term undersupply with pilot oil can be compensated via this accumulator.

Sizing data: see operation manual.

Please also consider the Parker accumulator product range and the Parker Accumulator Sizing Software.

Block circuit diagram electronics

Connection diagrams electronics



Please order plugs separately.



ProPxD interface program

The ProPxD software allows quick and easy setting of the digital valve electronics. Individual parameters as well as complete settings can be viewed, changed and saved via the comfortable user interface. Parameter sets saved in the non-volatile memory can be loaded to other valves of the same type or printed out for documentation purposes.

The PC software can be downloaded free of charge at www.parker.com/isde – see page "Support" or directly at

www.parker.com/propxd.

Features

- Comfortable editing of valve parameters
- · Saving and loading of customized parameter sets
- Executable with all Windows[®] operating systems from Windows[®] XP upwards
- Simple communication between PC and valve electronics via serial interface RS232C

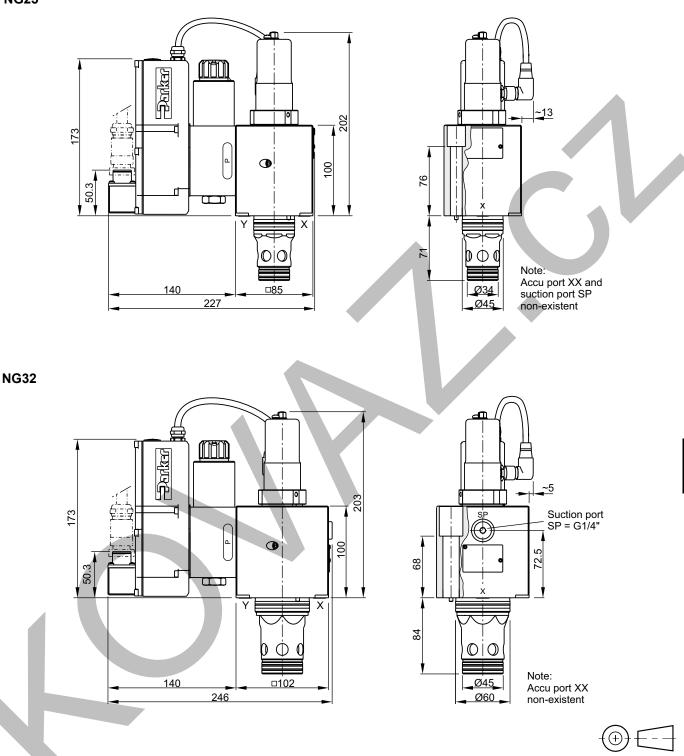
The valve electronics cannot be connected to a PC with a standard USB cable – this can result in damages of PC and/or valve electronics.

The parametrizing cable may be ordered under item no. 40982923.

e Options Diagnostics	Specia	ls Help I	8		
basic	all Par	rm.			
PC settings		PC		Modul	Module setting:
	No.	Value	Description	Module	
	P1	0.0	Zero Adjust [%]		no modul
	P3	100.0	Max [%] A-channel		
D*1FC dig.	P4	100.0	Max [%] B-channel		Design series
	P7	0.0	Min [%] A-channel		????
alve	P8	0.0	Min [%] B-channel		Version
274 (<u>5</u>	S5	0	ramp up [ms] A		2777
	S6	0	ramp down [ms] A		Valve
default	S7	0	ramp up [ms] B		
	S8	0	ramp down [ms] B		Channel "A"
					2222
					Channel "B"
					2777
				8	
					Parko
nput					
	-			3 3	
Upper limit 90.0					Receive all
	-	-			
Lower limit -90.0	-				
				8	Send all
			-		
P1 = 0.0					
Update list					
				-	Default



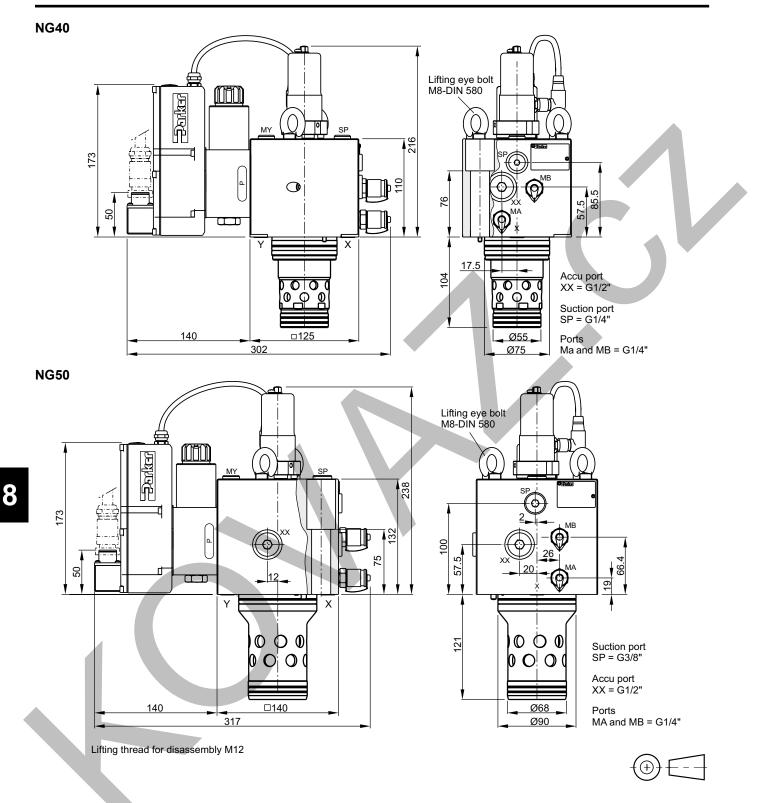
NG25



Suction port SP: Contact Parker for installation recommendation.

NG	Bolt kit - 町丁子		🔘 Kit					
NG	Bolt kit - 🗐 🖓	5	NBR	FPM				
25	BK504 4 x M12x100 ISO 4762-12.9	108 Nm	SK-TDP025EN30	SK-TDP025EV30				
32	BK529 4 x M16x100 ISO 4762-12.9	264 Nm	SK-TDP032EN30	SK-TDP032EV30				



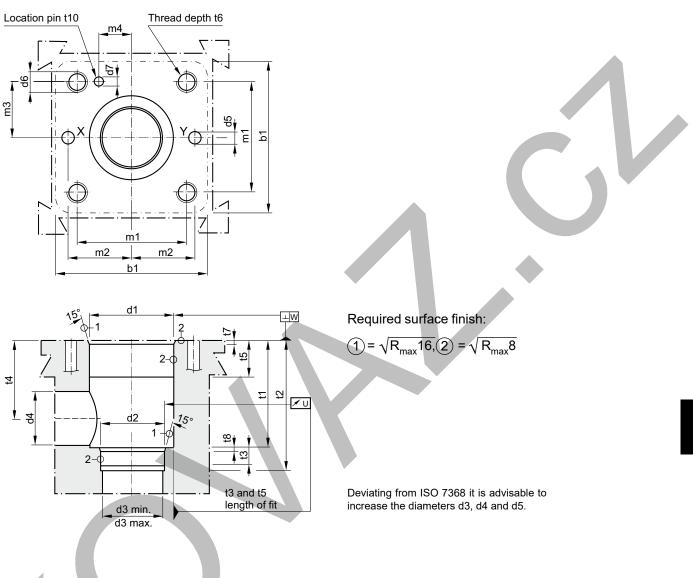


Suction port SP: Contact Parker for installation recommendation.

NG	Bolt kit - 파 - F		🔘 Kit					
NG	Bolt kit - 🗐 🖓	5	NBR	FPM				
40	BK481 4 x M20x110 ISO 4762-12.9	517 Nm	SK-TDP040EN30	SK-TDP040EV30				
50	BK481 4 x M20x110 ISO 4762-12.9	517 Nm	SK-TDP050EN30	SK-TDP050EV30				



Code: ISO 7368-B*-*-2-A/B NG25 to NG50



Size	b1	d1 H7	d2 H7	d3 / d4	d3 max	d4 max ¹⁾	d 5	d6	d7 H13	m1±0.2	m2±0.2	m3±0.2
25	85	45	34	25	27	32	6	M12	4	58	33	29
32	102	60	45	32	44	50	8	M 16	6	70	41	35
40	125	75	55	40	54	63	10	M 20	6	85	50	42.5
50	140	90	68	50	67	80	10	M 20	8	100	58	50

Size	m4±0.2	t1+0.5	t2+1	t3	t4	t4 max.1)	t5	t6	t7	t8	t10	U	W
25	16	58	72	12	44	40.5	30	35	25	25	10	0.03	0.05
32	17	70	85	13	52	44	15	35	2.5	2.5	10	0.03	0.1
40	23	87	105	15	64	54	15	45	3	3	10	0.05	0.1
50	30	100	122	17	72	59	17	45	4	3	10	0.05	0.1

 $^{1)}\,d4$ max. only in combination with t4 max.

